

Bootloader for CC2510, CC2511, CC1110 and CC1111 SoC (System-on-Chip) Transceivers

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Keywords

- *Bootloader*
- *Firmware Update*
- *Flash read/write*
- *SPI interface*
- *DMA controller*
- *Boot loader testing*

1 Introduction

This document describes the details of a boot loader which can be used for the CC2510, CC2511, CC1110 or CC1111 SoC transceivers. It covers the overall flow of the boot loader, a line by line description of the code, the test environment to test/drive the boot loader and sample LED blinking code to verify the functionality of the boot loader. Whenever the chip gets reset, control jumps to the starting point of the boot loader where, based on the validity of the firmware (i.e., application code), the boot loader will either accept commands from the user and program the new firmware into the flash or will directly jump to the starting point of the already existing valid

firmware in the flash. So the task of the boot loader is to validate the firmware present in the flash and then decide to either program the user specified firmware or jump to the existing firmware. This boot loader code is derived from the boot loader for the CC2530 [1]. Based on the transceiver used, define CC2510, CC2511, CC1110 or CC1111 in the options → C/C++ Compiler → Preprocessor → Defined symbols in IAR embedded work bench.

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2 Introduction to the boot loader

This section gives an introduction to the boot loader for the CC2510/1 & CC1110/1 SoC transceivers (in this document, we will refer to CC2510/1 and CC1110/1 transceivers as SoCs). A boot loader is mainly used to load the program (user code) into the code memory area of the microcontroller. It is the first thing that is performed after the microcontroller is powered up. In the case of the SoCs, the user code needs to be written into the internal flash memory of the SoCs. In order to load the user code into the internal flash, there should be a small program present inside the internal flash that performs the task of interacting with the external world and writing the user code into the specified location of internal flash. This set of code is called the boot loader. After reset, the program counter of the microcontroller is always set to the starting point of the boot loader. The boot loader will first look for valid user code (by looking at the CRC words stored in a specific location of internal flash) in the internal flash. If it finds valid user code, then control jumps to the starting point of the user code. Before entering the user code, there is a fixed wait time of a small duration, during which the microcontroller can be forced to enter the boot loader execution sequence. In the boot loader execution sequence, the user may write new user code into the internal flash. [1][2][5]

Figure 1 shows the block diagram of the SoC showing its flash memory, boot loader code location, user code location and external host that interacts with the boot loader to write the user code.

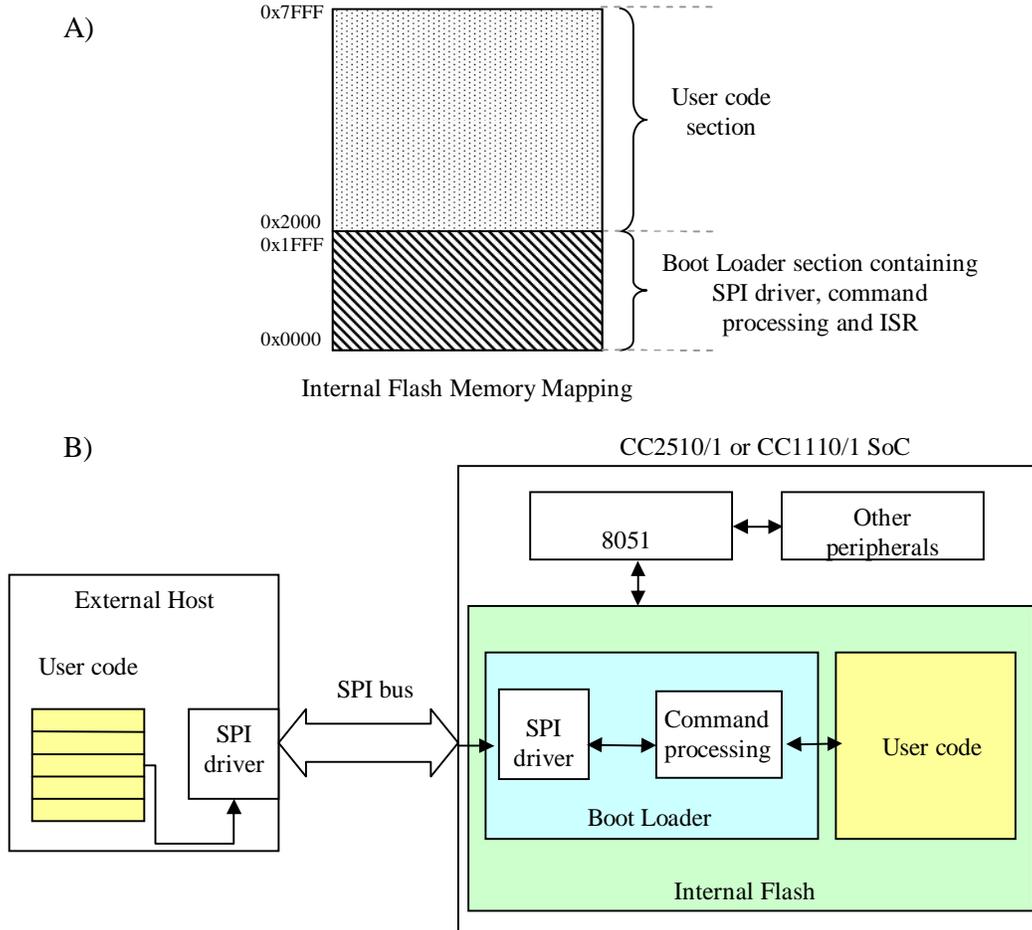


Figure 1 (A) Mapping of internal flash memory (B) Block diagram of CC2510/1 & CC1110/1 SoCs along with boot loader, user code and external host.

2.1 Overall flow of the boot loader

Figure 2 shows the flow chart of the boot loader code [6]. After reset, the SoC is initialized; i.e., its USART port is configured as SPI, the clock is set and the directions and values of I/O ports and DMA are configured for writing data into flash. After configuration is done, valid user code is looked for in the user code location. This is done by looking at CRC words, which were computed and written by the external host along with user code. If a valid CRC word is found, then there is a wait cycle of around 1 minute (this wait time is programmable and can be made much shorter if desired, please refer to Figure 6) during which a SB_FORCE_BOOT or SB_FORCE_RUN command could be given to the boot loader from the external host.

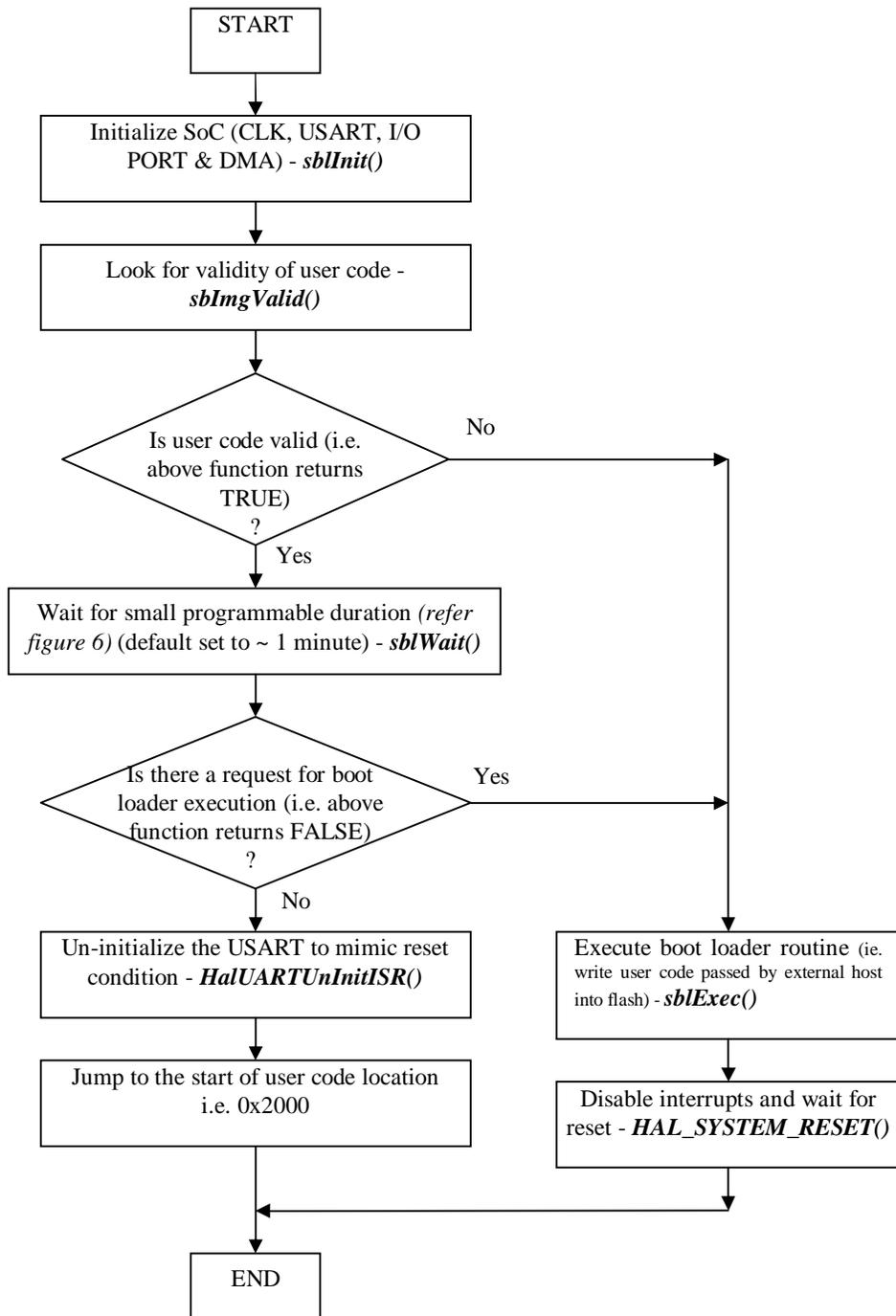


Figure 2 Flow chart of the boot loader [6].

If a SB_FORCE_RUN command is given, then control jumps to the predefined start of user code, and if a SB_FORCE_BOOT command is given, then the boot loader routine is executed. A SB_FORCE_RUN command can be generated by the external host by passing 0x07 to the boot loader through the SPI bus, and a SB_FORCE_BOOT command is given by passing 0xF8. If neither of the two commands is given during this wait cycle, control will jump

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to the start of user code by default at the end of this wait cycle. Before jumping to the user code, USART interrupts are reset to avoid false trigger in the user code.

During the CRC word validation check, if an invalid CRC word was detected (i.e. no valid user code is present), then control jumps to the execution of boot loader routine. This boot loader routine is used to write valid user code into the user code area of the internal flash of the SoCs. There is a state machine that runs in this routine that looks for a valid frame format (discussed later) generated by the external host and then performs the tasks accordingly. After the complete user code is written into the flash, an enable command is generated by the external host, which will bring the control out of the boot loader routine, and then control can jump to the newly written user code.

Figure 2 also shows the function names which are called at various stages of the flow.

sbllnit() → Initializes clock, USART, I/O ports and DMA of the SoC.

sbImgValid() → Looks for validity of the user code by looking at the CRC word. It returns TRUE when valid user code is found and FALSE when there is no valid user code in the flash and the boot loader routine needs to be run.

sbIWait() → Waits ~1 min during which a SB_FORCE_RUN or SB_FORCE_BOOT command can be issued by external host. This function returns TRUE when user code needs to be run and FALSE when the boot loader routine needs to be executed.

sbIExec() → Executes the boot loader routine that interacts with an external host to write valid user code into the internal flash of the SoC.

HalUARTUnInitISR() → Resets all the interrupts and configuration registers related to USART to their reset values.

HAL_SYSTEM_RESET() → Disables interrupts and waits for reset.

3 Code description

This section gives a detailed description of the boot loader code. Figure 3 shows the function call graph of the boot loader code [6]. Functionality of most of these functions has been described in the previous section. We will go through each function line by line.

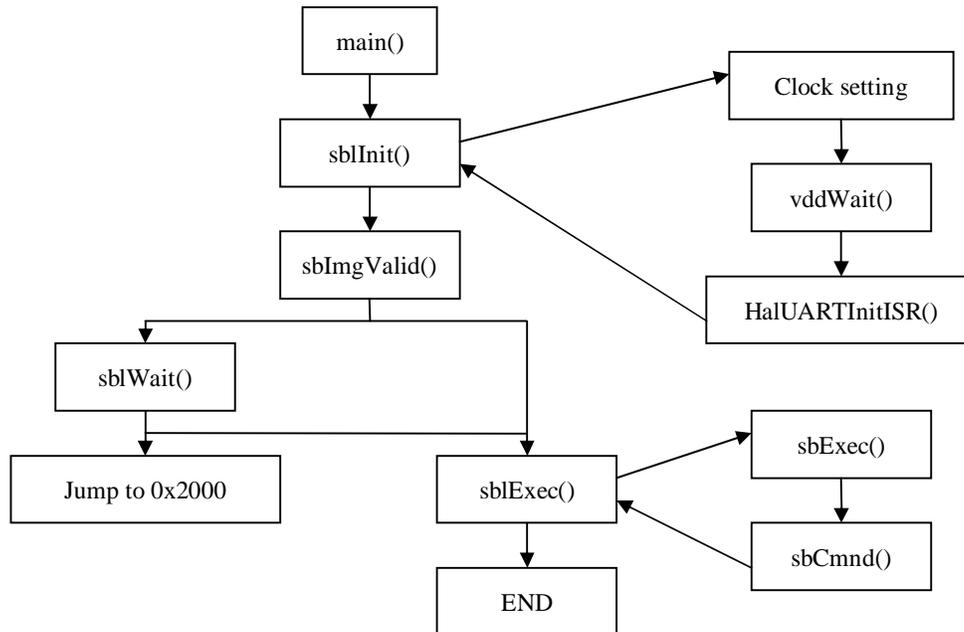


Figure 3 Call graph of the boot loader.

Figure 4 shows the snap shot of the main function. First, the sbIInit() function is called, which will configure the SoC parameters. Then the sbImgValid() function is called, which will check for valid user code. If it finds valid user code, it will return TRUE and control will enter the first “if” loop.

```

void main(void)
{
  sbIInit();
  if (sbImgValid())
  {
    if (sbIWait())
    {
      HalUARTUnInitISR();
      // Simulate a reset for the Application code by an absolute jump to location 0x2000.
      asm("LJMP 0x2000\n");
      HAL_SYSTEM_RESET();
    }
  }
  sbIExec();
  HAL_SYSTEM_RESET();
}
  
```

Annotations for Figure 4:

- sbIInit(); ← Initialize boot loader
- if (sbImgValid()) ← Check for validity of user code
- if (sbIWait()) ← Check for voltage level of Vdd
- asm("LJMP 0x2000\n"); ← Jump to location 0x2000 where user code is written
- sbIExec(); ← Execute boot loader code

Figure 4 Snap shot of the main function [1].

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If FALSE is returned, then the “if” condition is not satisfied, so control will skip the loop and will call the `sblExec()` function, which is the boot loader routine to interact with the external host and write valid user code into the internal flash of SoC. If the `sblWait()` function is called, then there is a wait time period of around 1 minute during which the boot loader will wait for `SB_FORCE_RUN` or `SB_FORCE_BOOT` commands from the external host. If none of these commands is received, then the function returns TRUE at the end of the wait time, and control jumps to the user code after resetting USART interrupt and configuration registers.

Now we will describe each function in detail.

3.1 `sblInit()`:

1. Setup Clock – These parameters can be changed if required by referring to the datasheet of the SoCs [3][7]
 - `SLEEP &= ~0x04;` //Turning on both the HS oscillator (HS XOSC and HS RCOSC).
 - `while(!(SLEEP & 0x40));` //Wait for HS XOSC to stabilize.
 - `CLKCON &= 0xBF;` //Selecting HS XOSC.
 - `while(CLKCON & 0x40);` //Check if HS XOSC was selected as system clock.
 - `SLEEP |= 0x04;` //Turn off the HS oscillator which was not selected as system clock (i.e. HS RCOSC is turned off).
2. Turn on cache pre-fetch mode
 - `FCTL = 0x08`
3. Set port P1 (to which LEDs are connected) as output ports. By default they are set as input ports.
4. Call `vddWait(VDD_MIN_RUN)`
 - It has a loop which checks for 16 cycles of ADC read value > `VDD_MIN_RUN`
5. Assign `magicByte = SB_MAGIC_VALUE` (i.e., `0xF5`)
 - Indicates whether bootloader or user code is active. It is used to decide the location of the interrupt vector table.
6. Configure DMA0 registers `DMA0CFGH` & `DMA0CFGL`
 - Used for writing the data (user code) into the flash
7. Call `HalUARTInitISR()`
 - USART is configured in SPI mode. Here it can be changed to UART mode.
 - Other settings associated with it, such as baud rate, flow control, etc is done.

3.2 `sblmgValid()`:

This function checks for validity of the user code. It does so by checking the CRC word that was stored in the flash while writing the user code. The boot loader computes the CRC of the user code and stores it in location `0x2090` and `0x2092` of flash. It keeps two copies of the computed CRC, which are used while validating the user code.

1. First it reads 2 words of CRC from the flash memory (i.e., locations `0x2090` & `0x2092`) and stores it in the local array `crc[0]` and `crc[1]`.
2. Then it checks if `crc[0] = 0xFFFF` (memory was flushed/erased) or `0x0000` (memory was invalidated). If so, then return FALSE which means user image is not valid.
3. If `crc[0]` is neither `0xFFFF` nor `0x0000`, then check if `crc[0] = crc[1]`. If not, then compute crc on the user code and compare it with the stored crc value in the flash. If they match, then the user code is valid and so return TRUE else return FALSE.

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Figure 5 shows snap a shot of the function `sblmgValid()` with the description of each line.

```
uint8 sblmgValid(void)
{
    uint16 crc[2];

    HalFlashRead(HAL_SB_CRC_ADDR / HAL_FLASH_PAGE_SIZE, ← Read CRC from Flash
                HAL_SB_CRC_ADDR % HAL_FLASH_PAGE_SIZE,
                (uint8 *)crc, sizeof(crc));

    if ((crc[0] == 0xFFFF) || (crc[0] == 0x0000)) ← Check for validity of
    {                                             CRC
        return FALSE;
    }

    if (crc[0] != crc[1])
    {
        crc[1] = calcCRC(); ← Compute CRC
        HalFlashWrite(HAL_SB_CRC_ADDR / HAL_FLASH_WORD_SIZE, (uint8 *)crc, 2); ← Write computed value
        HalFlashRead( HAL_SB_CRC_ADDR / HAL_FLASH_PAGE_SIZE,                                     of CRC into Flash
                    HAL_SB_CRC_ADDR % HAL_FLASH_PAGE_SIZE,
                    (uint8 *)crc, sizeof(crc));
    }
    return ((crc[0] == crc[1]) && (crc[0] != 0xFFFF) && (crc[0] != 0x0000)); ← Read CRC from Flash
}
}
```

Figure 5 Snap shot of function `sblmgValid()` [1].

3.3 `sblWait()`:

This function returns TRUE if user code should be run, false otherwise (i.e., the boot loader routine should be run). The control reaches this function only if the user code is valid, i.e., it has passed CRC check.

There are two cases when this function returns TRUE:

1. `dlyCnt` counter time out.
2. data read from the USART buffer is `SB_FORCE_RUN` (i.e. 0x07)

There is one case when this function returns FALSE:

1. data read from the USART buffer is `SB_FORCE_BOOT` (i.e. 0xF8)

Logic could be added in this function such that instead of a command, a button press could be used (i.e., asserting one of the I/O pins and using it as an indication for the `SB_FORCE_BOOT` or `SB_FORCE_RUN` command) for deciding what to run, user code or the boot loader routine.

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```
static uint8 sb1Wait(void)
{
    uint32 dlyCnt = 0x100000;
    uint8 rtn = FALSE;
    HAL_ENABLE_INTERRUPTS();

    while (1)
    {
        uint8 ch;

        if (HalUARTReadISR(&ch, 1))
        {
            if (ch == SB_FORCE_BOOT)
            {
                break; //return FALSE
            }
            else if (ch == SB_FORCE_RUN)
            {
                dlyCnt = 0; //return TRUE
            }
        }

        /*if (SB1_PRESS)
        {
            break;
        }*/

        if (SB2_PRESS || (dlyCnt-- == 0))
        {
            rtn = TRUE; //return TRUE
            break;
        }

        // RR-xing LED display while waiting.
        if (dlyCnt & 0x2000)
        {
            SB_TURN_OFF_LED2();
            SB_TURN_ON_LED1();
        }
        else
        {
            SB_TURN_OFF_LED1();
            SB_TURN_ON_LED2();
        }
    }

    HAL_DISABLE_INTERRUPTS();
    SB_TURN_OFF_LED1();
    SB_TURN_OFF_LED2();

    return rtn;
}
```

This counter controls the wait time before jumping to user code. Change this value to increase or decrease the wait time.

Read data from USART buffer and return TRUE or FALSE based on command received

If counter "dlyCnt" has reached zero, then return TRUE

Blink LEDs to indicate wait cycle in process

Figure 6 Snap shot of the function sb1Wait() [1].

3.4 HalUARTUninitISR():

Before jumping to the user code at location 0x2000, we need to reset the USART. So we disable UTX0IE interrupt, UxCSR, URX0IE, URX0IF & UTX0IF. This is done to return the USART to the state it would normally be in after a Hard Reset event.

3.5 sb1Exec():

1. It checks for the VDD voltage level.
2. It enables interrupts.
3. Finally, it waits in the infinite loop till the sbExec() function returns TRUE. sbExec() returns TRUE when an ENABLE command is given by the external host to the boot loader, which means that complete valid user code is written into the flash memory and the CRC is updated.

3.6 sbExec():

This function contains the state machine that controls the reading/writing of the code into and out of the flash memory.

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It also reads data from the USART buffer. Based on the value received, the next state of the state machine is decided.

Case SB_SOF_STATE:

If data is SB_SOF (i.e., 0xFE)

next state = SB_LEN_STATE

Case SB_LEN_STATE:

If data is > SB_BUF_SIZE (i.e., 128)

next state = SB_SOF_STATE

Else

next state = SB_CMD1_STATE

Case SB_CMD1_STATE:

next state = SB_CMD2_STATE

Case SB_CMD2_STATE:

If length != 0

next state = SB_DATA_STATE

Else

next state = SB_FCS_STATE

Case SB_DATA_STATE:

If all the data have been received

next state = SB_FCS_STATE

Case SB_FCS_STATE:

If CMD1 = SB_RPC_SYS_BOOT (i.e., 0x4D)

next state = SB_SOF_STATE

Call sbCmnd()

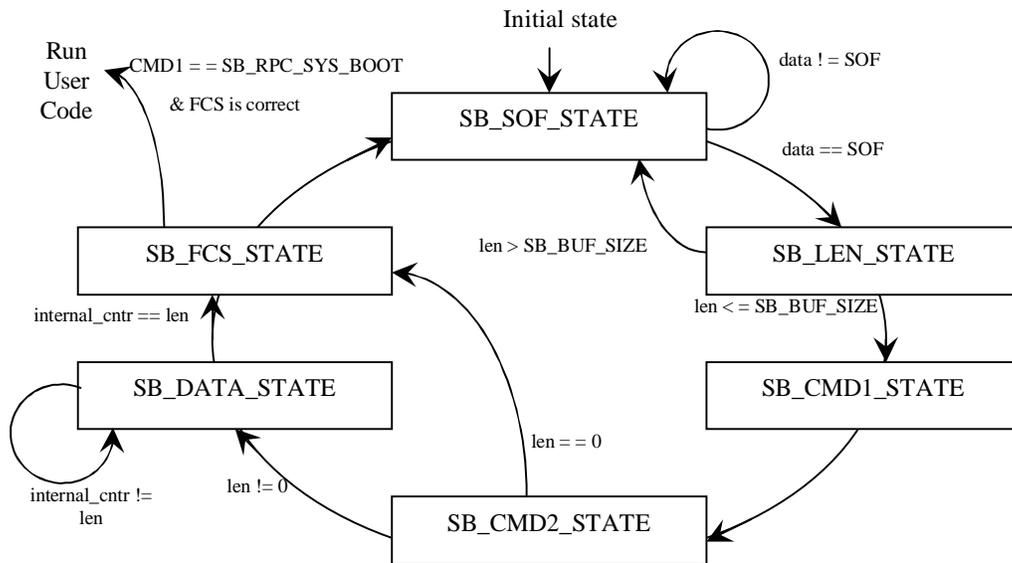


Figure 7 State machine of function sbExec().

3.7 sbCmnd():

This function performs the task as commanded in the CMD2, such as flash read and write. It returns TRUE or FALSE. TRUE is returned when ENABLE_CMD is sent from host and a viable user code image exists.

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Case SB_HANDSHAKE_CMD:

Return FALSE

Case SB_WRITE_CMD:

Erase flash

Write data into flash

Return FALSE

Case SB_READ_CMD:

Read data from flash

Return FALSE

Case SB_ENABLE_CMD:

Read CRC from flash

Check CRC bytes to find the validity of the user code

If CRC is correct

Return TRUE

Else

Return FALSE

Command 2 (CMD2)	Task	Description
0x01	Flash Write	Writes 64 bytes of data into internal flash of SoC. Starting address is specified in the first two bytes of the 66 bytes of the data field of the write frame.
0x02	Flash Read	Reads 64 bytes of data from internal flash of SoC. Starting address is specified in the 2 bytes of data field of the read frame.
0x03	Enable Command	After complete user code is written into the flash, a frame is sent with the enable command, which will bring control out of the boot loader routine.
0x04	Hand Shake	This command should be given before writing user code into flash, just to confirm that execution of boot loader routine has begun.

Table 1 Different types of commands which can be given to the boot loader [1].

Note: Each location in the flash should be erased before writing into it. If the location is not erased before writing, the flash will not be written to the correct value. This is because during a write operation, a flash bit can be changed from a high to a low value, but the bit cannot be changed from low to high [3][7]. This can only be done by an erase command. Erasing a flash will set all the bits of a flash. Now, when a write request comes for writing logic 0, the bit will be changed from 1 to 0 and for writing 1, the bit will be kept unchanged. The smallest unit which can be erased in a flash is called a "Page," which is 1024 bytes in the case of the CC2510/1 and CC1110/1 SoCs [3][7]. We cannot erase one location at a time; we have to erase one complete page at a time. In this boot loader, we give write requests of 64 bytes at a time. The function sbCmnd() erases the page whenever there is a write request at the starting location of that page. For example whenever there is a request for a write command at location 0x0000 (word address), that means there is a write request at location 0x2000 to 0x2040 (as there is an internal offset of 0x2000 added to the address field, refer to Figure 12 Command frame format.). So page 8 is erased. There will not be a page erase request for other locations within that page, such as 0x2040, 0x2080, etc. Page erase requests come for the following byte addresses: 0x2400, 0x2800, 0x2C00 and so on (LSB 10 bits are zero). In short, the external host cannot start writing from the middle of the page. It will have to start writing from the first location of the page.

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```

static uint8 sbCmdnd(void)
{
    uint16 tmp = BUILD_UINT16(sbBuf[SB_DATA_STATE], sbBuf[SB_DATA_STATE+1]) + SB_IMG_OSET;
    uint16 crc[2];
    uint8 len = 1;
    uint8 rsp = SB_SUCCESS;
    uint8 rtn = FALSE;

    switch (sbCmd2)
    {
    case SB_HANDSHAKE_CMD:
        break;

    case SB_WRITE_CMD:
        if ((tmp % SB_WPG_SIZE) == 0)
        {
            HalFlashErase(tmp / SB_WPG_SIZE);
        }

        HalFlashWrite(tmp, sbBuf+SB_DATA_STATE+2, SB_RW_BUF_LEN / HAL_FLASH_WORD_SIZE);
        break;

    case SB_READ_CMD:
    #if !MT_SYS_OSAL_NV_READ_CERTIFICATE_DATA
        if ((tmp / (HAL_FLASH_PAGE_SIZE / 4)) >= HAL_NV_PAGE_BEG)
        {
            rsp = SB_FAILURE;
            break;
        }
    #endif
        HalFlashRead(tmp / (HAL_FLASH_PAGE_SIZE / 2/*4*/),
                    (tmp % (HAL_FLASH_PAGE_SIZE / 2/*4*/) << 1/*2*/,
                    sbBuf + SB_DATA_STATE + 3, SB_RW_BUF_LEN);
        sbBuf[SB_DATA_STATE+2] = sbBuf[SB_DATA_STATE+1];
        sbBuf[SB_DATA_STATE+1] = sbBuf[SB_DATA_STATE];
        len = SB_RW_BUF_LEN + 3;
        break;

    case SB_ENABLE_CMD:
        HalFlashRead(HAL_SB_CRC_ADDR / HAL_FLASH_PAGE_SIZE,
                    HAL_SB_CRC_ADDR % HAL_FLASH_PAGE_SIZE,
                    (uint8 *)crc, sizeof(crc));

        // Bootload master must have verified extra checks to be issuing the SB_ENABLE_CMD.
        //if ((crc[0] != crc[1]) && (crc[0] != 0xFFFF) && (crc[0] != 0x0000))
        if (crc[1] != crc[0])
        {
            crc[1] = crc[0];
            HalFlashWrite((HAL_SB_CRC_ADDR / HAL_FLASH_WORD_SIZE), (uint8 *)crc, 1);
            HalFlashRead( HAL_SB_CRC_ADDR / HAL_FLASH_PAGE_SIZE,
                        HAL_SB_CRC_ADDR % HAL_FLASH_PAGE_SIZE,
                        (uint8 *)crc, sizeof(crc));
        }

        // Bootload master must have verified extra checks to be issuing the SB_ENABLE_CMD.
        //if ((crc[0] == crc[1]) && (crc[0] != 0xFFFF) && (crc[0] != 0x0000))
        if (crc[0] == crc[1])
        {
            rtn = TRUE;
        }
        else
        {
            rsp = SB_VALIDATE_FAILED;
        }
        break;

    default:
        break;
    }

    sbResp(rsp, len);
    return rtn;
}

```

Offset of 0x2000 added to the address specified by the external host

Erase Flash

Flash Write Data

Flash Read Data

Flash Read CRC

CRC Check for user code validation

Figure 8 Snap shot of the function sbCmdnd() [1].

3.8 ISR in the boot loader

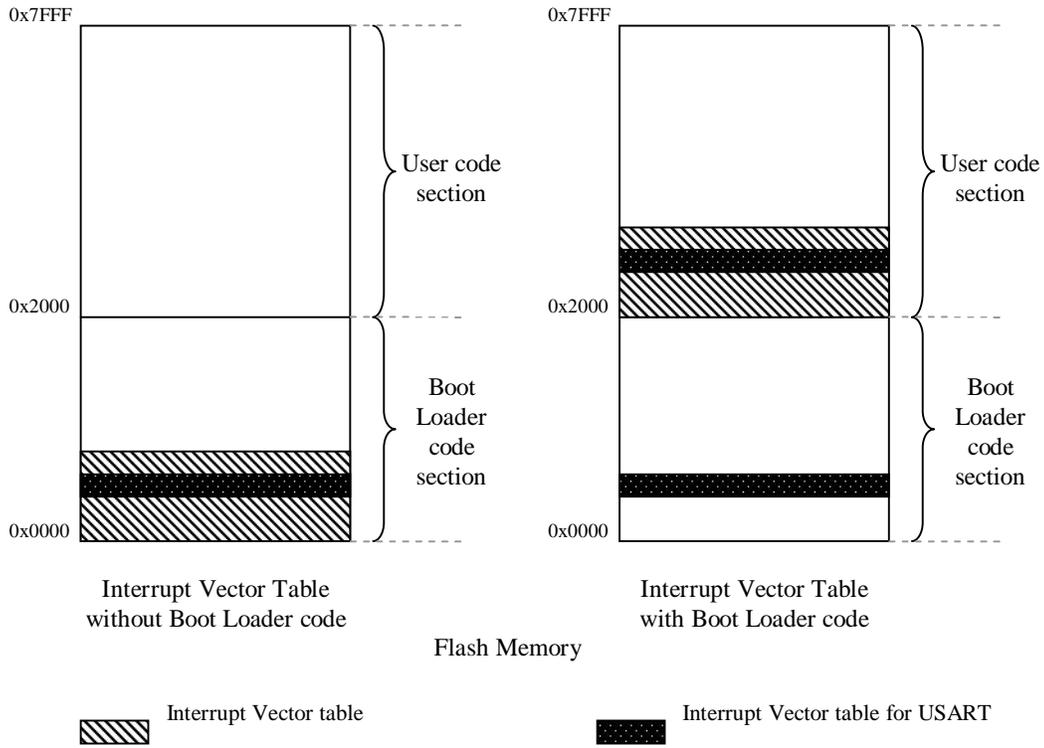


Figure 9 Flash Memory mapping of Interrupt Vector Table.

There is a variable called `magicByte` that stores the value `SB_STACK_VALUE` (i.e. `0xCD`) or `SB_MAGIC_VALUE` (i.e. `0xF5`) [1]. Whenever a USART interrupt occurs, the value in the variable `magicByte` is checked; if it is `0xCD`, then control jumps to the ISR in the user code, else if the value is `0xF5`, it is handled locally in the boot loader. In the boot loader mode, this variable will have value `0xF5` (it is assigned in the `sbInit` function). All other vectors jump directly to the user vector.

```

HAL_ISR_FUNCTION( halUartRxDmaIsr, URX0_VECTOR )
{
    if (magicByte == SB_STACK_VALUE)
    {
        void (*rxIsr)(void);
        rxIsr = (void (*)(void))0x2013;
        rxIsr();
    }
    else if (magicByte == SB_MAGIC_VALUE)
    {
        halUartRxDmaIsr();
    }
    else
    {
        asm("NOP"); // Not expected.
    }
}

HAL_ISR_FUNCTION( halUartTxDmaIsr, UTX0_VECTOR )
{
    if (magicByte == SB_STACK_VALUE)
    {
        void (*txIsr)(void);
        txIsr = (void (*)(void))0x203B;
        txIsr();
    }
    else if (magicByte == SB_MAGIC_VALUE)
    {
        halUartTxDmaIsr();
    }
    else
    {
        asm("NOP"); // Not expected.
    }
}

```

Figure 10 Snap shot of UART ISR functions [1].

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The boot loader code should be linked using the sb_boot.xcl linker command file [5]. This file contains the appropriate placement for the boot loader in the first segment of flash. The user code should be linked with an appropriately modified linker command file which places the magicNumber variable at location 0x0001, and the ISR vector table for the user code placed at address 0x2000. Also, the CRC word (16-bits) should be placed at addresses 0x2090-0x2091 and 0x2092-2093 (or word address 0x1048 and 0x1049). Both the locations should have the same CRC word value.

NOTE:

Upon entering the user code (suggested first thing in main) and before any interrupts are enabled, the user must write the SB _STACK_VALUE to the location referenced by the magicNumber variable. Failure to do so will cause UART interrupts to be ignored or possibly run the boot loader ISR rather than the user ISR. Only after this value is written is it safe for the user code to enable interrupts.

3.9 DMA controller for flash write

The DMA controller is used to write data (user code), which is received from the external host, into the internal flash of the SoC, in chunks of 64 bytes (32 words). (Please refer to the Flash Controller chapter of CC2510/1 or CC1110/1 datasheet for details on DMA flash write [3][7].) In this boot loader, channel 0 of the DMA is used. All DMA parameters such as source address, destination address, transfer count, byte/word transfer, etc., are written into a local structure called "dmaCh0," and the address of this structure is written into the DMA configuration register DMA0CFGH (0xD5) and DMA0CFGH (0xD4). By setting the values of this structure (dmaCh0), all the parameters of DMA (channel 0) will be set, and, when a trigger event occurs, the DMA will transfer 4 bytes, 1 byte at a time, to the FWDATA register. The DMA trigger is set on Flash data write complete; i.e., whenever a flash data write event occurs, the DMA will start its iteration of writing the data into the FWDATA register → incrementing the source address → looking at the number of remaining data to transfer (please refer to DMA controller section 12.5 of CC2510/1 or CC1110/1 datasheet). [3][7]

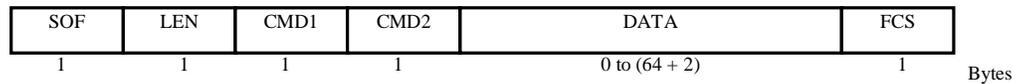
All the parameters of DMA are given below:

1. Source address (SRCADDR) (16-bits) – address where the received user code is temporarily stored in SRAM
2. Destination address (DESTADDR) (16-bits) – address of the FWDATA register, i.e., 0x6273
3. Transfer count (16-bits) – 64, i.e., 64-bytes are transferred for each write command.
4. Byte or word transfer (1-bit) – '0', i.e., 1-byte at a time
5. Transfer mode (TMODE) (2-bits) – '00', i.e., single transfer mode
6. Trigger event (TRIG) (5-bits) – '10010', i.e., trigger DMA on flash data write complete
7. Source increment (SRCINC) (2-bits) – '01', i.e., increment source address by 1
8. Destination increment (DESTINC) (2-bits) – '00', i.e., does not increment the destination address as the destination address is FWDATA.
9. Interrupt mask (IRQMASK) (1-bit) – '0', i.e., disable interrupt generation
10. Mode 8 setting (M8) (1-bit) – '0', i.e., use all 8-bits for transfer count
11. DMA priority (PRIORITY) (2-bits) – '10', i.e., DMA access will always prevail over CPU access

After all these parameters are set, the flash address where data needs to be stored is written in its configuration registers FADDH:FADDL, and then FCTL.WRITE is set. This will trigger the DMA write and will wait till FCTL.BUSY becomes zero, i.e., the flash write is complete.

4.1 Command from external host

Data to be written or read from the flash memory through the boot loader needs to be requested in a fixed frame format. The frame consists of six fields: SOF, LEN, CMD1, CMD2, DATA and FCS [1]. All the fields are of 1 byte except for the DATA field. During a write command, the DATA field will be of 66 bytes: 2 bytes of flash address at which the data needs to be written and 64 bytes of data to be written in flash. The frame format is shown in Figure 12.



<p>Byte 0: SOF: Start of Frame = 0xFE</p> <p>Byte 1: LEN: Length of data = 0x00, 0x02 or 0x42</p> <p>Byte 2: CMD1: Command 1 = 0x4D</p> <p>Byte 3: CMD2: Command 2 = 0x01, 0x02, 0x03 or 0x04</p> <p>Byte 4-69: DATA: First two bytes are Flash address and next 64 bytes are data.</p> <p style="padding-left: 40px;">Byte 4: Lower byte of word address* (if LEN is non-zero)</p> <p style="padding-left: 40px;">Byte 5: Higher byte of word address* (if LEN is non-zero)</p> <p style="padding-left: 40px;">Byte 6-69: 64 bytes of data (if LEN > 2)</p> <p>Byte 70: FCS: Frame Check Sequence = XOR of whole frame from LEN to last byte of DATA.</p>
<p>CMD2: 0x01: Flash Write</p> <p style="padding-left: 20px;">0x02: Flash Read</p> <p style="padding-left: 20px;">0x03: Enable command</p> <p style="padding-left: 20px;">0x04: Hand Shake</p>

* 1 word = 16-bits. As 64 bytes i.e. 32 words are written on each write command, the address field should be incremented by 0x0020 for each consecutive write command. Also, there is internal offset of 0x2000 added to this address field before using it to address the flash. So, 0x0000 means location 0x2000 of flash.

Figure 12 Command frame format.

CMD2 can be one of the following four commands: flash write, flash read, enable and handshake. If user code needs to be written in the flash, then the flash write command can be used. The flash address needs to be provided while writing into the flash. It is written in the first two bytes of the data field followed by 64 bytes of data. In case of a flash read, there will be only two bytes of data field which will contain 2 bytes of address from where the data is to be read. In response to a flash read command, the boot loader will read 64 bytes of data, starting from the address specified in the flash read command frame and will write it into USART buffer. When the external host is reading the response, it will have to read out 72 bytes (4 bytes of header, 1 byte of response, 2 bytes of address, 64 bytes of data and 1 bytes of FCS). When complete user code is written in the flash memory, then a frame with the ENABLE command needs to be sent so that the boot loader code knows that the valid user code is written into the flash, and so control should come out of boot loader.

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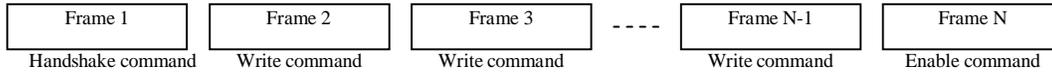


Figure 13 Typical sequence of command to write user code.

Figure 13 shows a typical sequence of frames to write user code into the flash memory. It starts with handshake frame, which just acknowledges the external host (who is issuing the command) that the boot loader routine is running. Then the external host can start sending frames with a write command to write the user code into specified flash addresses (starting with 0x0000 and then incrementing by 0x0020 for each write command). Once the whole user code is written into the flash, a frame with an enable command is issued that will inform the boot loader that valid user code has been written into the flash and so boot loader execution should end and control should jump to the user code. Before giving the enable command, a read command can be used to read the flash and verify that the user code is written correctly into the flash (optional).

Note: The data (which is the user code) passed through the frame is in binary format. Data is directly written into the flash without any processing or modification on it.

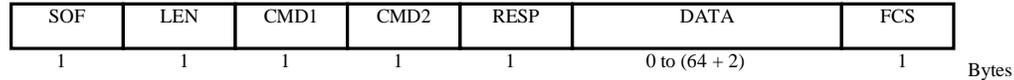
Insert CRC word (16-bits) at two locations:

Word address - 0x0048 and 0x0049 (0x1000 will be added by boot loader)

In terms of byte address it will be 0x0090-0x0091 and 0x0092-0x0093. (0x2000 will be added by boot loader)

4.2 Response to the command

Each frame is acknowledged with an appropriate response. The response frame format is similar to the frame format discussed above. Figure 14 shows the response frame format:



Byte 0: SOF: Start of Frame = 0xFE

Byte 1: LEN: Length of data = 0x01 or 0x43 (*it includes RESP + DATA length*)

Byte 2: CMD1: Command 1 = 0x4D

Byte 3: CMD2: Command 2 = 0x81, 0x82, 0x83 or 0x84 (CMD2 is ORed with 0x80)

Byte 4: RESP: Response

0 = SB_SUCCESS: If not the below two cases

1 = SB_FAILURE: If address is beyond the mapping address of
Flash memory

7 = SB_VALIDATE_FAILED: If CRC validation fails

Byte 5-70: DATA*: First two bytes are Flash address and next 64 bytes are data. (*valid only for the response of read command*)

Byte 5: Lower byte of word address

Byte 6: Higher byte of word address

Byte 7-70: 64 bytes of data

Byte 71: FCS: Frame Check Sequence = XOR of whole frame from LEN to last byte of DATA.

CMD2: 0x81: Response for Flash Write

0x82: Response for Flash Read

0x83: Response for Enable command

0x84: Response for Hand Shake

* For all request except for read request, there will be no DATA field.

Figure 14 Response frame format.

Figure 15 shows four set of command frames which can be generated by the external host and its corresponding response frame given by boot loader.

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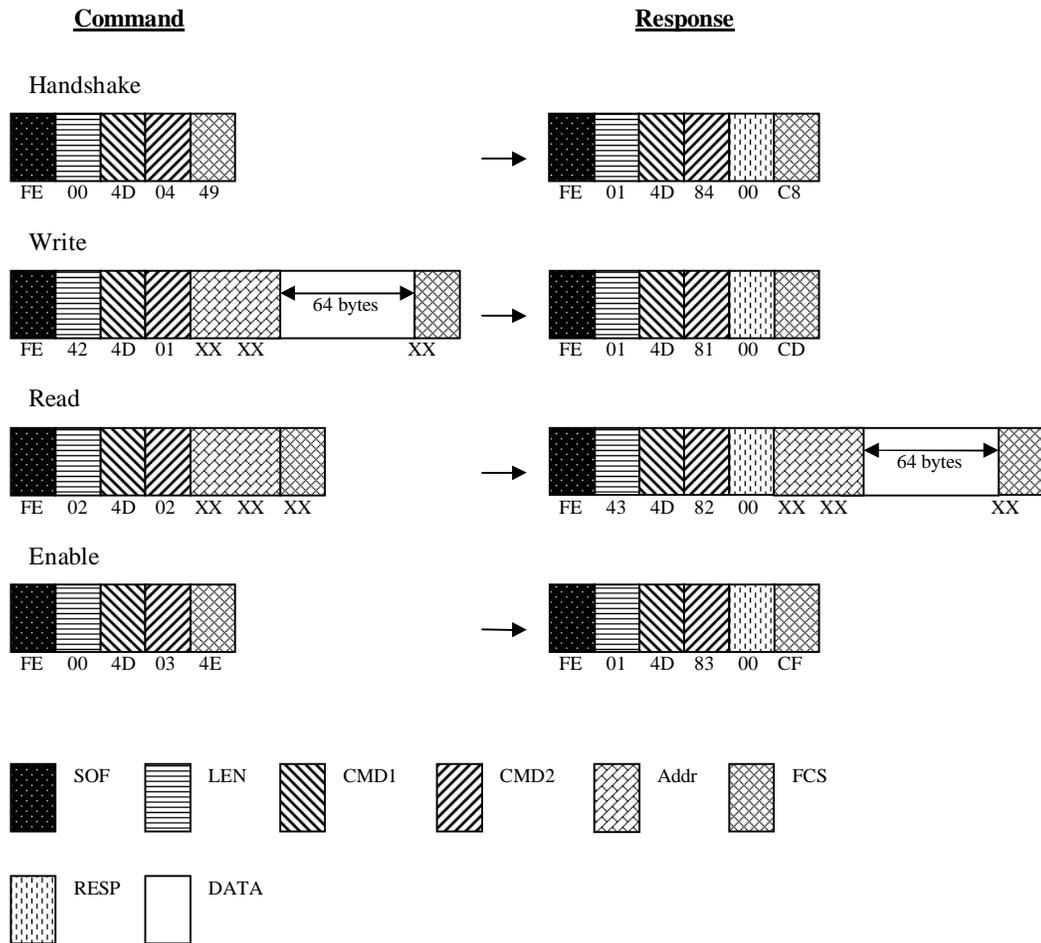


Figure 15 Command frame and its corresponding response frame.

Figure 16 shows waveforms for the data transfer on the SPI bus. As seen in the waveforms, read and write cycles are exactly same. The only difference is that, in a write cycle, SIMO is driven with valid data and the SoC will drive SOMI with the value present in its TXBUF. In case of a read cycle, SIMO can be driven with any value (say 0x00) other than the key bytes (like 0xFE, 0x4D, etc) which represents the command to the SoC, and the SOMI value is sampled on each rising edge of SCLK. In short, the SoC will always read the value of SIMO and store it in its internal RXBUF and will always drive value stored in TXBUF on the SOMI pin.

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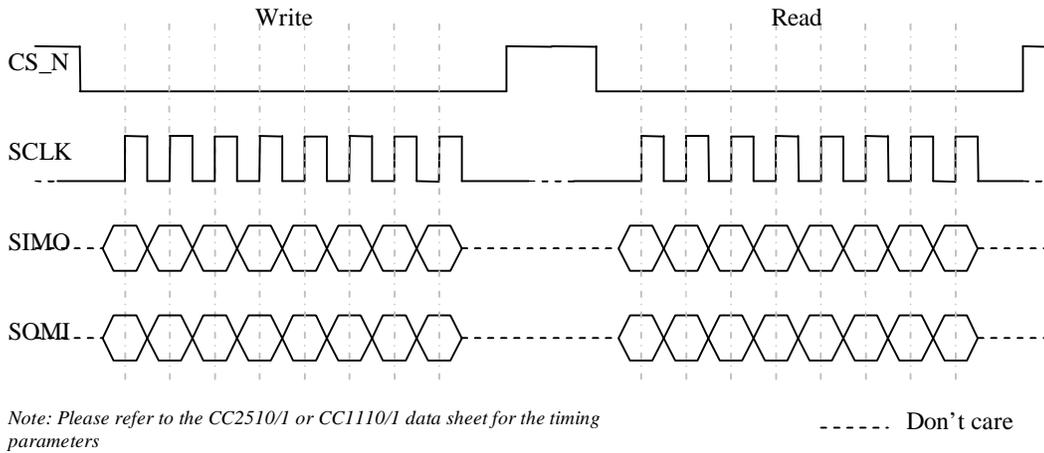


Figure 16 Waveform for data transfer on SPI bus [4].

5 Test Environment

In this section, we describe the setup used for burning the boot loader code into the location 0x0000 to 0x1FFF (byte address) of the internal flash using IAR embedded workbench for 8051 and the interface with the external host, which will be writing valid user code into locations 0x2000 to 0x7FFF (byte addresses) of the internal flash of the SoC.

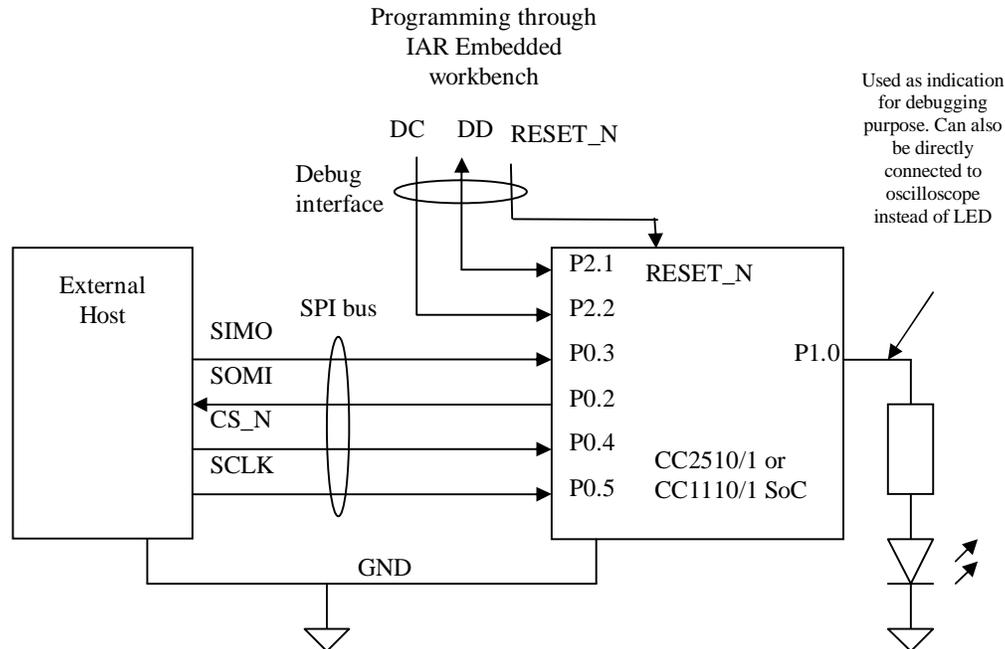


Figure 17 Test Environment setup to burn the boot loader code into SoCs and to interact with external host for writing valid user code into the internal flash of SoCs.

[3][4][7] The SPI interface is used to communicate between an external host and the boot loader. This can be easily changed to a UART interface by just configuring USART registers in the HalUARTInitISR() function. Port P1.0 is set as an output port, which can be used as indication at various stages of the code (for debugging purposes). To program the SoC with the boot loader code using IAR Embedded workbench, the P2.1 and P2.2 pins are used as debug data and debug clock pins respectively. The code is built and programmed through IAR workbench by opening the workspace: \$PROJ_DIR\boot_loader\boot.eww. In this setup, Port 0 is configured in SPI mode. Port 1 can also be used instead of Port 0. This can be done in sbllnit() function. Make sure to define CC2510, CC2511, CC1110 or CC1111 in the options → C/C++ Compiler → Preprocessor → Defined symbols in IAR embedded work bench, based on which SoC the boot loader is being burned. This will include the appropriate I/O header file from the following folder: <IAR installed folder>\8051\inc\ioCC2510.h (or ioCC2511.h / ioCC1110.h / ioCC1111.h). IAR workbench version 7.6 was used for building this project, so it's recommended to use this or any newer version.

6 Sample LED blinking code

To verify if the boot loader is writing the user code passed by the external host correctly, we used a sample LED blinking program and generated the binary file from IAR Embedded work bench. The procedure is described below:

A small LED blinking code is written as shown below:

```
#include <hal_types.h>
#include <hal_defs.h>
#include <hal_cc8051.h>
#include <ioCCxx10_bitdef.h>
#include <ioCC2510.h>

int main(void)
{
    unsigned char i,j;
    // Initialize P1_1/3 for SRF04EB LED1/3
    P1SEL &= ~(BIT3 | BIT0);
    P1_0 = 1; P1_3 = 1;
    P1DIR |= (BIT3 | BIT0);

    while(1)
    {
        P1_0 ^= 1;
        for (i=0;i<0xFF;i++){for (j=0;j<0xFF;j++){}}
    }

    return 0;
}
```

Then generate output hex file in intel format.

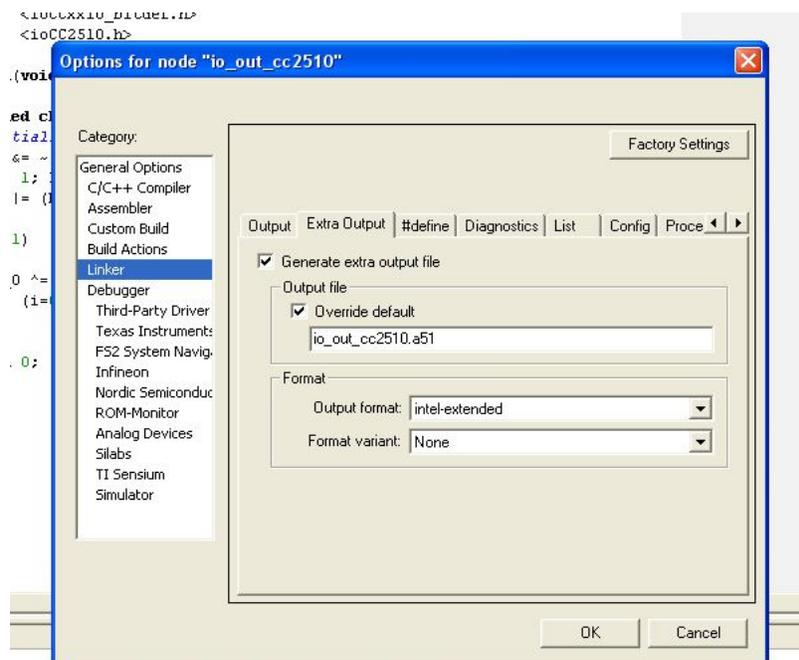


Figure 18 Generating the Intel Hex format file

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Before compiling and generating the Intel Hex file, we will have to change the starting address of the code in the linker file to 0x2000. This is done because we are not writing the code at location 0x0000; we are relocating it to location 0x2000, and if the compiler used absolute jump instead of relative jump commands, control would move to the wrong location and the code might hang. Figure 19 shows the snap shot of the IAR workbench showing the path of the linker file where the starting address needs to be changed [8].

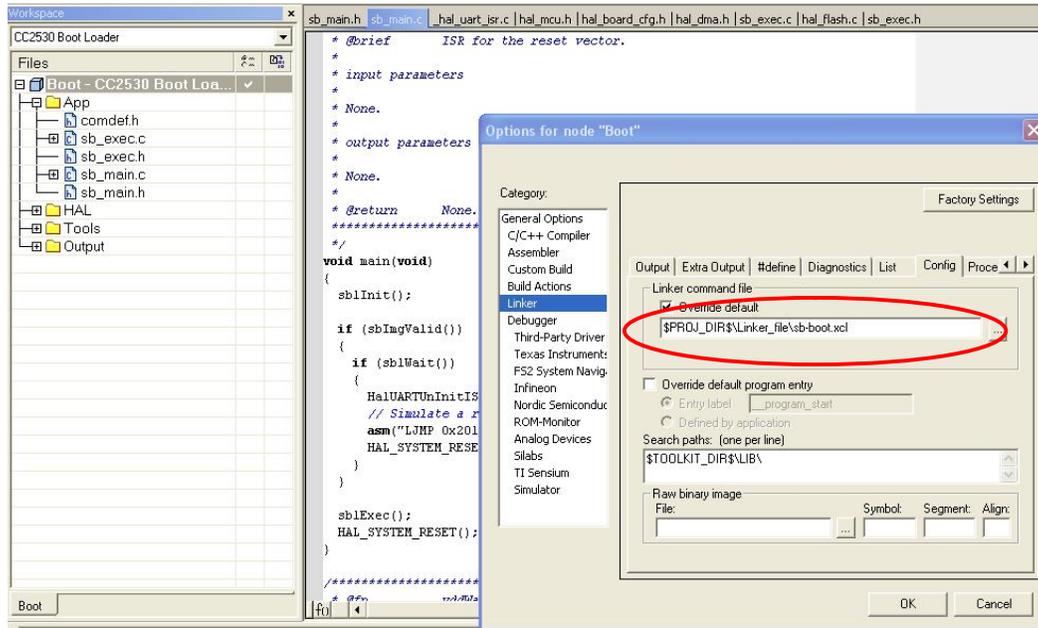


Figure 19 Changing the program starting address

It will generate a file in standard Intel HEX file format [9] as shown below:

```
:020000040000FA
:100000000200170000080FB120020B9000302006C
:100010001112002312000375D0007581BF02000881
:1000200079012253F4F6E5F4D290D29343FE09E528
:10003000FE639001E5907B0080080AEAC394FF40CC
:0C004000F90BEBC394FF50E97A0080EF4D
:0400000500000017E0
:00000001FF
```

[Blue: DATA, RED: location to which instruction pointer must point at the beginning]

Binary data could be extracted from this file and driven as user code from external host. In the drop-down list of format, there is another format called “msp430-txt” which will generate text file with binary value of the code as shown below:

```
02 00 17 00 00 00 80 FB 12 00 20 B9 00 03 02 00
11 12 00 23 12 00 03 75 D0 00 75 81 BF 02 00 08
79 01 22 53 F4 F6 E5 F4 D2 90 D2 93 43 FE 09 E5
```


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7 FAQ

Q1. Is there any option of specifying the start address of the application code (i.e., the address with which the program counter must be loaded initially to run the application code)?

Ans. Yes. There is a LJMP command in the main() function (sb_main.c) which specifies the starting point of the user code. For example, suppose the user code is written from 0x2000 to 0x3000 but the starting point of the application code is 0x2017. Then, the instruction pointer must be loaded with 0x2017, which is done by the command **asm("LJMP 0x2017\n")** in the main() function. You can change this address to the starting address of your application code.

Q2. What all changes are required if I need to change the bootloader reserved code space?

Ans. You will require two changes:

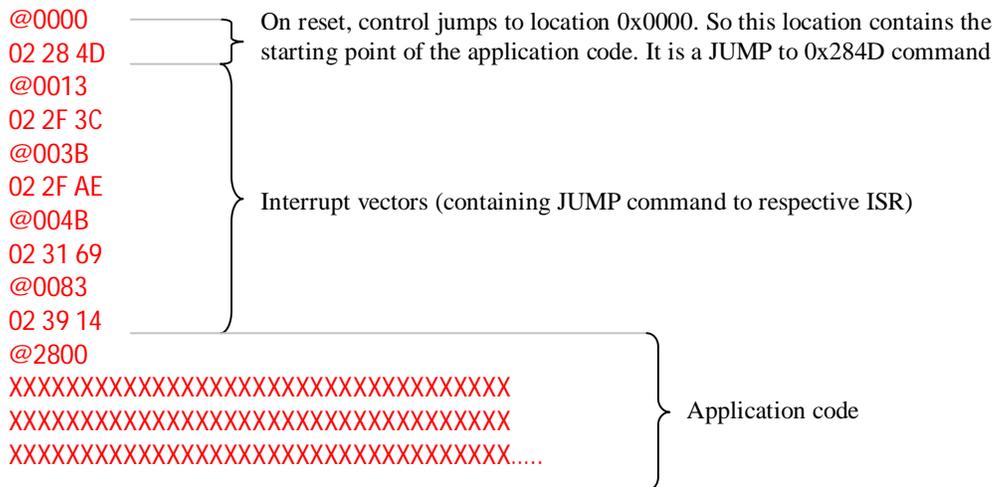
1. Change `-D_CODE_END` variable in `sb-boot.xcl`
2. Change the offset added to the address sent through the read/write command. This is done by changing these two values in `hal_board_cfg.h`
 - a. `#define HAL_SB_IMG_ADDR 0x2000`
 - b. `#define HAL_SB_CRC_ADDR 0x2090`

`HAL_SB_IMG_ADDR` will change the offset added and `HAL_SB_CRC_ADDR` indicates the location where computed CRC value is stored. This will also change if boot loader code space increases or decreases.

Q3. While generating application code starting at (for example) location 0x2800, there are some values generated at locations between 0x0000 to 0x008F. What are these and do we need to write these values into flash?

Ans. These are interrupt vectors at locations: 0x0003, 0x000B, 0x0013, 0x001B, 0x0023, 0x002B ... till 0x008B. These are total 18 interrupt vectors.

Let's consider an example. Suppose after generating the hex file, you get



Please follow the below steps to handle these interrupts:

1. Open file `interrupt_stubs.s51`. There is an offset defined as 0x2000 at line 40. As the boot loader code area is increased to 0x2800, make this offset as 0x2800 (or whatever is the boot loader code area). What this will do is, for example, write "jump

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- to 0x284B” at location 0x004B when you burn the boot loader code into the SoC (it will do this for all the interrupt vectors). So whenever a timer 1 interrupt comes, the 8051 will move to location 0x004B where the jump to 0x284B command will be written. This way all the interrupt vectors are forwarded to the interrupt vector starting at location 0x2800.
2. In the file `interrupt_stubs.s51`, you will see that “USART0 RX complete” and “USART0 TX complete” interrupt vectors are commented out. This is because these two interrupts are also used by the boot loader, so we cannot directly forward these interrupts to location 0x2813/0x283B. Whenever one of these two interrupts occurs, the 8051 will move to location 0x0013 or 0x003B (based on the RX/TX interrupt), and there will be jump command that will jump to the if condition within the boot loader code area defined in file `sb_main.c` (line 379). In this if condition, it checks if boot loader code is running or the application code is running. If the boot loader code is running, this interrupt is handled internally by the boot loader (by calling function `halUartRxIsr()` or `halUartTxIsr()`), otherwise it jumps to location 0x2013 or 0x203B. Just change the location value at line 384 from 0x2013 to 0x2813 and at line 402: from 0x203B to 0x283B. This will ensure that when interrupt was from the application code, control jumps to the location 0x2813 or 0x283B
 3. There are 18 interrupt vectors (0x2803, 0x280B, 0x2813, 0x281B, 0x2823, 0x282B,...) starting from 0x2803 to 0x288B. So you will have to skip these values while writing application code. Better to start the application code at 0x2900. So change the `-D_CODE0_START` value to 0x2900 instead of 0x2800 and again generate the `msp430-txt` format file.
 4. Now you will get new values for @0013, @003B, @004B and @0083. Write those values at location 0x00XX (i.e. 0x0003, 0x000B, 0x0013, 0x001B...) or 0x28XX (i.e., 0x2803, 0x280B, 0x2813, 0x281B...). Remember that the current boot loader supports only 64 bytes of write command. So if you would like to write these interrupt vectors at location 0x28XX, write it as shown below:

```
@0x2800
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
```

```
@0x2840
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
```

```
@0x2880
FF FF FF 02 XX XX FF FF FF FF FF 02 XX XX FF FF
FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
```

(numbers in red are the jump command of the four interrupts generated after compilation)
(You can start writing at location 0x2800 and fill 0xFF in all the intermediate locations (i.e. non-interrupt vector locations))

You can write FF for the interrupts which you are not using. So there will be 3 write requests of 64 bytes each. As address given during write command is word address, you will have to give 0x1400, 0x1420 and 0x1440 for the three write commands. In this case you will have to write 0x2813 and 0x283B in the `HAL_ISR_FUNCTION()` in file `sb_main.c`

8 References

8.1 Cited references

- [1] CC253x Bootloader code in ZigBee protocol stack for CC2530 - <http://focus.ti.com/docs/toolsw/folders/print/z-stack.html>
- [2] CC253x SoC User's Guide - <http://focus.ti.com/docs/prod/folders/print/cc2530.html>
- [3] CC2510/1 datasheet - <http://focus.ti.com/docs/prod/folders/print/cc2510f32.html>
- [4] TI design note DN113 on CC111xFx, CC243xFx, CC251xFx and CC253xFx SPI interface - <http://www.ti.com/lit/swra223>
- [5] Serial Boot Loader for CC253x SoC, Document number: SWRA327 <http://focus.ti.com/docs/toolsw/folders/print/z-stack.html>
- [6] CC2510/1 & CC1110/1 Bootloader code - <http://www.ti.com/litv/zip/swra371>
- [7] CC1110/1 datasheet - <http://focus.ti.com/docs/prod/folders/print/cc1110f32.html>

8.2 General references

- [8] IAR Embedded workbench - <http://www.iar.com/website1/1.0.1.0/3/1/>
- [9] http://en.wikipedia.org/wiki/Intel_HEX

9 Document History

Revision	Date	Description/Changes
1.0	06/08/2011	Initial release.
1.1	09/07/2011	Support for CC2511, CC1110 and CC1111.

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